

Kernel relaxation for space-filling design¹

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1 Three space-filling criteria

\mathcal{X} = a compact subset of \mathbb{R}^d , $\mathcal{X} = \text{cl}(\text{int}(\mathcal{X}))$; $f: \mathcal{X} \rightarrow \mathbb{R}$
use pairs $(\mathbf{x}_i, f(\mathbf{x}_i))$, $i = 1, \dots, n$, to approximate or integrate f over \mathcal{X}

With little prior information about f

→ observe “everywhere”

→ choose a design $\mathbf{X}_n = \{\mathbf{x}_1, \dots, \mathbf{x}_n\}$ space-filling in \mathcal{X}

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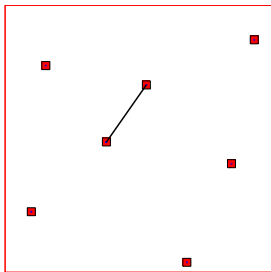
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We shall consider three “classical” criteria:

- 1 Packing radius
- 2 Covering radius
- 3 L_S -quantisation error

1/ **Packing radius**: maximise $\text{PR}(\mathbf{X}_n) \triangleq \frac{1}{2} \min_{i \neq j} \|\mathbf{x}_i - \mathbf{x}_j\|$

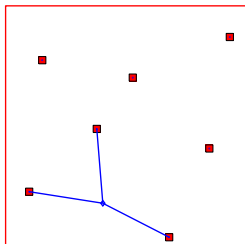
$\text{PR}(\mathbf{X}_n)$ = separation radius = $\frac{1}{2}$ Maximin distance criterion



- can often be related to numerical stability issues
- easy to compute, but pushes points to the boundary of \mathcal{X}

2/ **Covering radius:** minimise $CR(\mathbf{X}_n) = CR_{\mathcal{X}}(\mathbf{X}_n) \triangleq \max_{\mathbf{x} \in \mathcal{X}} \min_{\mathbf{x}_i} \|\mathbf{x} - \mathbf{x}_i\|$

$CR(\mathbf{X}_n)$ = fill distance = dispersion = miniMax distance criterion



- we are never far from a design point
- more difficult to compute
- appears in bounds on approximation error

(Narcowich et al., 2005; Schaback and Wendland, 2006)

3/ L_s -mean quantisation error:

μ a prob. measure on \mathcal{X} (equiv. to Lebesgue measure Λ)

$$\text{minimise } E_{s,\mu}(\mathbf{X}_n) \triangleq \left[\int_{\mathcal{X}} \left[\underbrace{\min_{\mathbf{x}_i} \|\mathbf{x} - \mathbf{x}_i\|}_{=d(\mathbf{x}, \mathbf{X}_n)} \right]^s d\mu(\mathbf{x}) \right]^{1/s}, \quad s > 0$$

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Optimal $\mathbf{X}_n^* = \underline{n\text{-optimal set of centers}}$,

a Voronoi partition of \mathbb{R}^d w.r.t. $\mathbf{X}_n^* = \underline{n\text{-optimal quantiser}}$;

see (Graf and Luschgy, 2000)

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$E_{s,\mu}(\mathbf{X}_n) \rightarrow$ bounds on worst-case approximation and integration errors

(Krieg and Sonnleitner, 2020)

\rightarrow general bounds on integ. error for Lipschitz functions (Pagès, 1997)

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For $s \geq 1$, $E_{s,\mu}(\mathbf{X}_n^*) = \min_{\mathbf{X}_n} E_{s,\mu}(\mathbf{X}_n) = \inf_{\mu_n \in \mathcal{P}_n} W_s(\mu, \mu_n)$, with

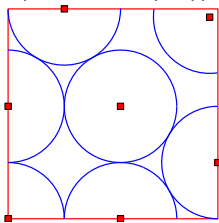
- \mathcal{P}_n = set of discrete probabilities on \mathbb{R}^d supported on n points

- $W_s(\mu, \mu')$ = L_s -Wasserstein (or Kantorovich) metric

$$= \inf_M \left(\int_{\mathbb{R}^d \times \mathbb{R}^d} \|\mathbf{x} - \mathbf{x}'\|^s dM(\mathbf{x}, \mathbf{x}') \right)^{1/s} \quad \text{with } M \text{ having marginals } \mu \text{ and } \mu'$$

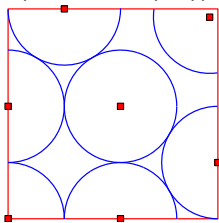
Example 1:

- ① Packing $d = 2, n = 7$
(radius=PR(\mathbf{X}_n))

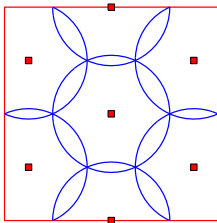


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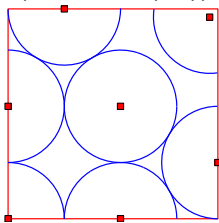


② Covering $d = 2, n = 7$
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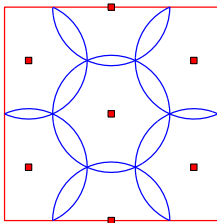


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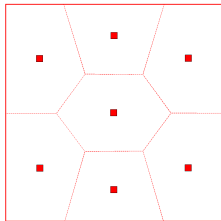
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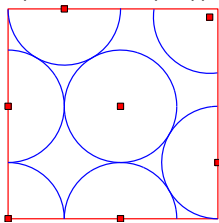


③ L_2 -quantisation,
 $d = 2, n = 7$

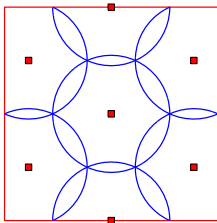


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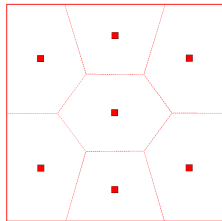
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③ L_2 -quantisation,
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→ Maximise $\text{PR}(\mathbf{X}_n)$, minimise $\text{CR}(\mathbf{X}_n)$ and $E_s(\mathbf{X}_n)$

2 Kernel relaxation

Some notation:

$\|\cdot\|$ is always the Euclidean norm in \mathbb{R}^d

For K a kernel on $\mathcal{X} \times \mathcal{X}$ (\rightarrow RKHS \mathcal{H}_K when K Pos. Def.),
 ν a signed measure on \mathcal{X} , define:

$$\mathcal{E}_K(\nu) \triangleq \int_{\mathcal{X}^2} K(\mathbf{x}, \mathbf{x}') d\nu(\mathbf{x})d\nu(\mathbf{x}') = \text{energy of } \nu$$

$$P_{K,\nu}(\mathbf{x}) \triangleq \int_{\mathcal{X}} K(\mathbf{x}, \mathbf{x}') d\nu(\mathbf{x}') = \text{potential of } \nu \text{ at } \mathbf{x}$$

$[P_{K,\nu}(\cdot) = \text{kernel imbedding of } \nu \text{ into } \mathcal{H}_K]$

Note that $\int_{\mathcal{X}} P_{K,\nu}(\mathbf{x}) d\nu(\mathbf{x}) = \mathcal{E}_K(\nu)$

Relaxation: example of the distance function

$$d(\mathbf{x}, \mathbf{X}_n) = \min_{\mathbf{x}_i \in \mathbf{X}_n} \|\mathbf{x} - \mathbf{x}_i\|$$

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$$\frac{1}{n} \sum_{i=1}^n \|\mathbf{x} - \mathbf{x}_i\|^{-q} \leq \max_{\mathbf{x}_i} \|\mathbf{x} - \mathbf{x}_i\|^{-q} \leq \sum_{i=1}^n \|\mathbf{x} - \mathbf{x}_i\|^{-q}$$

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with $K_q(\mathbf{x}, \mathbf{x}') = \|\mathbf{x} - \mathbf{x}'\|^{-q}$ the Riesz kernel with parameter q
 (K_q is singular, does not define a RKHS)
 and ξ_n the empirical measure on \mathbf{X}_n

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For n fixed, $[P_{K_q, \xi_n}(\mathbf{x})]^{-1/q} \rightarrow d(\mathbf{x}, \mathbf{X}_n)$, uniformly in \mathbf{x} and \mathbf{X}_n , as $q \rightarrow \infty$

Relaxation with other kernels than K_q :

$K(\mathbf{x}, \mathbf{x}') = \psi(\|\mathbf{x} - \mathbf{x}'\|)$ (isotropic) with

$\psi: [0, \infty) \mapsto (0, +\infty]$ continuous, strictly decreasing ($\psi(0) = \infty$ is allowed)

→ inverse function $\psi^{(-1)}(u)$ defined for $u \in (0, \psi(0)]$ and strictly decreasing too

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In particular: γ -exponential family $K_{\gamma, \ell}(\mathbf{x}, \mathbf{x}') = \exp[-\|\mathbf{x} - \mathbf{x}'\|^\gamma / (\gamma \ell^\gamma)]$, $\gamma > 0$
 $\gamma = 1 \rightsquigarrow$ exponential (Matérn 1/2) kernel, $\gamma = 2 \rightsquigarrow$ Gaussian kernel
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$$\boxed{-\gamma \ell^\gamma \log n} - \gamma \ell^\gamma \log P_{K_{e, \gamma, \ell, \xi_n}}(\mathbf{x}) \leq d^\gamma(\mathbf{x}, \mathbf{X}_n) \leq -\gamma \ell^\gamma \log P_{K_{e, \gamma, \ell, \xi_n}}(\mathbf{x}).$$

For n fixed, $-\gamma \ell^\gamma \log P_{K_{e, \gamma, \ell, \xi_n}}(\mathbf{x}) \rightarrow d^\gamma(\mathbf{x}, \mathbf{X}_n)$, uniformly in \mathbf{x} and \mathbf{X}_n , as $\ell \rightarrow 0$

3 Maximisation of the packing radius

ℓ_q -relaxation of $\text{PR}(\mathbf{X}_n) = \frac{1}{2} \min_{i,j} \|\mathbf{x}_i - \mathbf{x}_j\|$

Maximise $\frac{1}{2} \underbrace{\left(\frac{2}{n(n-1)} \sum_{i < j} \|\mathbf{x}_i - \mathbf{x}_j\|^{-q} \right)^{-1/q}}_{\text{for some } q > 0 \text{ (large)}}$

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$$\text{equivalent to minimise } \mathcal{E}_{K_q}^{\neq}(\mathbf{X}_n) = \frac{2}{n(n-1)} \sum_{i<j} \|\mathbf{x}_i - \mathbf{x}_j\|^{-q} \text{ (= discrete energy)}$$

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→ **continuous version:**

$$\text{PB1: minimise } \boxed{\int_{\mathcal{X}^2} \|\mathbf{x} - \mathbf{x}'\|^{-q} d\xi(\mathbf{x})d\xi(\mathbf{x}')} = \mathcal{E}_{K_q}(\xi) \text{ w.r.t. } \xi$$

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$\rightarrow \text{PR}(\mathbf{X}_n)$ as $q \rightarrow \infty$

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For $q \geq d$, $\mathcal{E}_{K_q}(\xi)$ is infinite for any non zero ξ

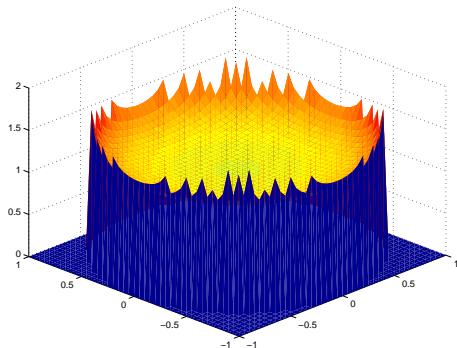
For $0 < q < d$ there exists a minimum-energy probability measure $\xi_{K_q}^+$

When $d - 2 < q < d$, $\xi_{K_q}^+$ has a density $\varphi_{K_q}^+$ in \mathcal{X}

and $P_{K_q, \xi_{K_q}^+}(\mathbf{x})$ is constant in \mathcal{X} ; see e.g. (Landkof, 1972)

Example 2: $\mathcal{X} = \mathcal{B}_d(\mathbf{0}, \rho)$

$d - 2 < q < d$: $\varphi_{K_q}^+(\mathbf{x}) = \frac{C}{(\rho^2 - \|\mathbf{x}\|^2)^{(d-q)/2}$, $\mathbf{x} \in \mathcal{X}$ (Landkof, 1972, p. 163)



$$d = 2, q = 7/4$$

(when $d > 2$ and $2 < q \leq d - 2$, $\xi_{K_q}^+$ is uniform on the sphere $\mathcal{S}_d(\mathbf{0}, \rho)$)

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There always exists a minimum-energy probability measure $\xi_{K_{\gamma,\ell}}^+$

For $K_{1,\ell}(\mathbf{x}, \mathbf{x}') = \exp(-\|\mathbf{x} - \mathbf{x}'\|/\ell)$ (the exponential kernel):

- For $d = 1$, $\mathcal{X} = [0, 1]$, $\xi_{K_\theta}^+ = 1/(1 + 2\ell)\Lambda(\mathcal{X}) + (\delta_0 + \delta_1)\ell/(1 + 2\ell)$
 $\rightarrow \xi_{K_{1,\ell}}^+$ has full support and $P_{K_{1,\ell}, \xi_{K_{1,\ell}}^+}(\mathbf{x})$ is constant on \mathcal{X}
- For $d > 1$, not full support: for $\mathcal{X} = \mathcal{B}_2(\mathbf{0}, 1)$, $\xi_{K_{1,\ell}}^+$ has positive mass on the surface of the circle and a spherically symmetric density in the interior of \mathcal{X} , equal to zero close to the boundary

Minimisation of $\mathcal{E}_K(\xi)$: main properties

If $\mathcal{E}_K(\cdot)$ is convex ($\gamma \in (0, 2]$ for $K_{\gamma, \ell}(\mathbf{x}, \mathbf{x}') = \exp[-\|\mathbf{x} - \mathbf{x}'\|^\gamma / (\gamma \ell^\gamma)]$)

- \rightarrow directional derivative (for bounded kernels)

$$\begin{aligned} F_{\mathcal{E}_K}(\xi, \delta_{\mathbf{x}}) &= \lim_{\alpha \rightarrow 0^+} \frac{\mathcal{E}_K[(1 - \alpha)\xi + \alpha\delta_{\mathbf{x}}] - \mathcal{E}_K(\xi)}{\alpha} \\ &= 2 [P_{K, \xi}(\mathbf{x}) - \mathcal{E}_K(\xi)] \end{aligned}$$

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$$\begin{aligned} F_{\mathcal{E}_K}(\xi, \delta_{\mathbf{x}}) &= \lim_{\alpha \rightarrow 0^+} \frac{\mathcal{E}_K[(1 - \alpha)\xi + \alpha\delta_{\mathbf{x}}] - \mathcal{E}_K(\xi)}{\alpha} \\ &= 2[P_{K, \xi}(\mathbf{x}) - \mathcal{E}_K(\xi)] \end{aligned}$$

- N&S condition for optimality (“Equivalence Theorem” – **ET**):

ξ_K^+ is optimal $\Leftrightarrow F_{\mathcal{E}_K}(\xi_K^+, \delta_{\mathbf{x}}) \geq 0$ for all $\mathbf{x} \in \mathcal{X}$

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Minimisation of $\mathcal{E}_K(\xi)$: main properties

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- (★) $\Rightarrow \min_{\mathbf{x} \in \mathcal{X}} P_{K, \xi}(\mathbf{x}) \leq \mathcal{E}_K(\xi)$ for any ξ , and thus

$$\xi_K^+ \text{ maximises } \min_{\mathbf{x} \in \mathcal{X}} P_{K, \xi}(\mathbf{x}) - \mathcal{E}_K(\xi)$$

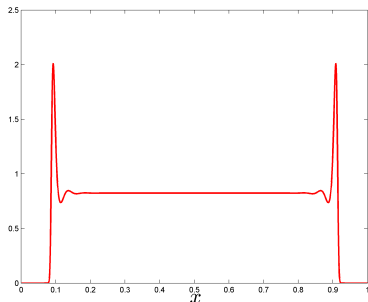
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Example 3: $\mathcal{X} = [0, 1]$, $K(x, x') = (1 + |x - x'|/\ell) \exp(-|x - x'|/\ell)$ (Matérn 3/2)

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→ Numerical determination of ξ_K^+ for $\ell = 1/(10\sqrt{3})$
 (2000 points equally spaced in $[0, 1]$, multiplicative algorithm)

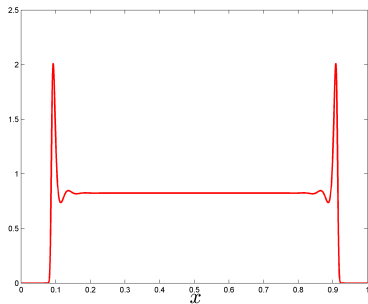
ξ_K^+ in $(0, 1)$ (with $\xi_K^+((0, 1)) \simeq 0.705$)



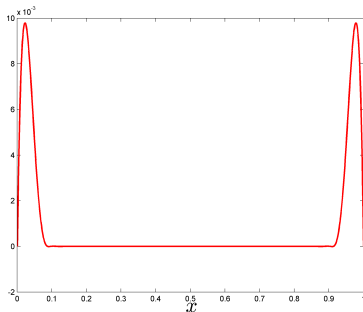
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$F_{\mathcal{E}_K}(\xi_K^+, \delta_x)$



$(\min_{x \in \mathcal{X}} F_{\mathcal{E}_K}(\xi_K^+, \delta_x) > -10^{-5})$

→ $F_{\mathcal{E}_K}(\xi_K^+, \delta_x) = 2[P_{K, \xi_K^+}(x) - \mathcal{E}_K(\xi_K^+)] \simeq 0$ on $\text{Supp}(\xi^+) \subset \mathcal{X}$

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→ Exact calculation of ξ_K^+ — see (P&Zh, 2023a)

$$\ell \geq \ell_0 \simeq 0.3980$$

$$\xi_K^+ = (\delta_0 + \delta_1)/2$$

$$\ell_0 > \ell \geq \ell_1 \simeq 0.3180$$

$$\xi_K^+ = m_0(\delta_0 + \delta_1) + (1 - 2m_0)\delta_{1/2}$$

(with $m_0 = m_0(\ell)$...)

$$\ell_1 > \ell$$

$$\xi_K^+ = m'_0(\delta_0 + \delta_1) + m_a(\delta_a + \delta_{1-a}) + \alpha\Lambda([a, 1 - a])$$

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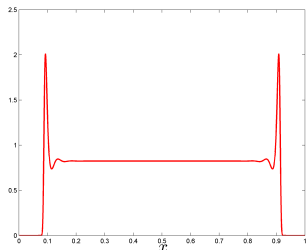
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→ For $\ell = 1/(10\sqrt{3})$,

$a \simeq 0.0908$ and

$$\xi_K^+((0, 1)) \simeq 0.6913$$



Discrete case: $\mathbf{X}_n \rightarrow$ empirical measure ξ_n

$$\mathcal{E}_K(\xi_n) = \text{var}(\hat{\theta}_{OLSE}^n) \text{ in } Y_{\mathbf{x}} = \theta + Z_{\mathbf{x}} \text{ with } E\{Z_{\mathbf{x}}\} = 0, E\{Z_{\mathbf{x}}Z_{\mathbf{x}'}\} = K(\mathbf{x}, \mathbf{x}')$$

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Greedy minimisation of $\mathcal{E}_K^\neq(\mathbf{X}_n)$, or Conditional gradient descent for $\mathcal{E}_K(\xi)$
 (= Frank-Wolfe = Wynn's vertex-direction alg.)

(P&Zh, 2023b): if

$q = q_n$ is such that $q_n / \log n \rightarrow \infty$ in $K_q(\mathbf{x}, \mathbf{x}') = \|\mathbf{x} - \mathbf{x}'\|^{-q}$, or

$\ell = \ell_n$ is such that $\ell_n n^{1/d} (\log n)^{1/\gamma} \rightarrow 0$ in $K_{\gamma, \ell}(\mathbf{x}, \mathbf{x}')$,

then $\liminf_{n \rightarrow \infty} \text{PR}(\mathbf{X}_n) / \text{PR}_n^* \geq 1/2$ and $\limsup_{n \rightarrow \infty} \text{CR}(\mathbf{X}_n) / \text{CR}_n^* \leq 2$

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General statements about $\text{Supp}(\xi_K^+)$:

- When K is PD, translation-invariant, with $K(\mathbf{x}, \mathbf{x}') = \Psi(\mathbf{x} - \mathbf{x}')$
 \rightarrow 2 conjectures (related to the non-existence of the continuous BLUE of β in the location model $Y(\mathbf{x}) = \beta + \varepsilon(\mathbf{x})$ where the errors $\varepsilon(\mathbf{x})$ have zero mean and covariance K)

- ξ_K^+ is not of full support when Ψ is differentiable at $\mathbf{0}_d$
- When $d > 1$, ξ_K^+ is not of full support unless K is singular

4 Minimisation of the covering radius

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Other kernels can be used, e.g., $K_{\gamma, \ell}(\mathbf{x}, \mathbf{x}') = \exp[-\|\mathbf{x} - \mathbf{x}'\|^\gamma / (\gamma \ell^\gamma)]$

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When $\mathcal{E}_K(\cdot)$ is convex, ξ_K^+ of **PB1** maximises $\min_{\mathbf{x} \in \mathcal{X}} P_{K, \xi}(\mathbf{x}) - \mathcal{E}_K(\xi)$
 if ξ_K^+ has full support, it is also optimal for **PB2**

true for $d = 1$ when $K(x, x') = \psi(|x - x'|)$ with ψ convex,
 and for any d when $K = K_q$ (Riesz), $q \in (d - 2, d)$

(... but we conjecture it is not the case when $d > 1$ for nonsingular kernels)

Doubly K -relaxed covering

relax max and min in $\text{CR}(\mathbf{X}_n) = \max_{\mathbf{x} \in \mathcal{X}} \min_{\mathbf{x}_i} \|\mathbf{x} - \mathbf{x}_i\| \approx \max_{\mathbf{x} \in \mathcal{X}} P_{K_q, \xi_n}^{-1/q}(\mathbf{x})$

$$\text{minimise } \left\{ \int_{\mathcal{X}} \left[P_{K_q, \xi}^{-1/q}(\mathbf{x}) \right]^q d\mu(\mathbf{x}) \right\}^{1/q} \quad \Rightarrow \quad \text{minimise } \int_{\mathcal{X}} P_{K_q, \xi}^{-1}(\mathbf{x}) d\mu(\mathbf{x})$$

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= convex problem (strictly when K ISPD and μ equivalent to Λ) \rightarrow **ET**

$$\xi^* \text{ is optimal} \Leftrightarrow \text{for all } \mathbf{x}' \in \mathcal{X}, \int_{\mathcal{X}} \frac{K(\mathbf{x}, \mathbf{x}')}{P_{K, \xi^*}^2(\mathbf{x})} d\mu(\mathbf{x}) \leq \int_{\mathcal{X}} P_{K, \xi^*}^{-1}(\mathbf{x}) d\mu(\mathbf{x})$$

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Discretisation of μ :

\rightarrow Replace μ by μ_N uniform on $\mathcal{X}_N = \{\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(N)}\}$

\rightarrow $\boxed{\text{minimise } \Phi_1[\mathbf{M}_K(\xi)] = \text{trace} \left[\frac{1}{N} \mathbf{M}_K^{-1}(\xi) \right]}$ (A-optimal design) with

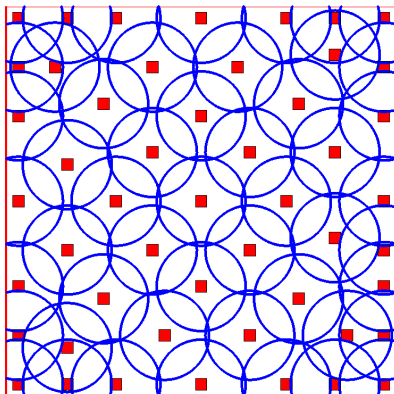
$$\mathbf{M}_K(\xi) = \text{diag}\{P_{K, \xi}(\mathbf{x}^{(j)}), j=1, \dots, N\} = \int_{\mathcal{X}} \text{diag}\{K(\mathbf{x}^{(j)}, \mathbf{x}), j=1, \dots, N\} d\xi(\mathbf{x})$$

(considered in (P&Zh, 2019) for $K = K_q$)

Example 4: $n = 50$ points in $\mathcal{X} = [0, 1]^2$ for K_q with $q = 10$

▸ incremental design by vertex-direction alg. ($\mathbf{x}_1 = (1/2, 1/2)$)

($\mathcal{X}_N = 33 \times 33$ regular grid, ξ supported on the 32×32 interlaced grid)



(radius = $\text{CR}(\mathbf{X}_n)$)

5 Minimisation of the L_s -mean quantisation error

ℓ_q -relaxation of $E_{s,\mu}(\mathbf{X}_n) = \left(\int_{\mathcal{X}} \min_{\mathbf{x}_i} \|\mathbf{x} - \mathbf{x}_i\|^s d\mu(\mathbf{x}) \right)^{1/s}$, $s > 0$

Replace $d(\mathbf{x}, \mathbf{X}_n) = \min_{\mathbf{x}_i} \|\mathbf{x} - \mathbf{x}_i\|$ by $[P_{K_q, \xi_n}(\mathbf{x})]^{-1/q}$

→ minimise $E_{K_q, s, \mu}(\mathbf{X}_n) = \left[\int_{\mathcal{X}} (P_{K_q, \xi_n}(\mathbf{x}))^{-s/q} d\mu(\mathbf{x}) \right]^{1/s}$ for $s, q > 0$

→ continuous version:

$$\text{PB3: minimise } e_{K_q, s, \mu}(\xi) = \left[\int_{\mathcal{X}} P_{K_q, \xi}^{-s/q}(\mathbf{x}) d\mu(\mathbf{x}) \right]^{1/s}, \quad s, q > 0$$

[= extension of (P&Zh, 2019) where only the case $q = s$ is considered]

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μ equivalent to Λ , $q \in (0, d) \rightarrow e_{K_q, s, \mu}^s(\cdot)$ is convex and differentiable → **ET**

ξ_q^* is optimal \Leftrightarrow for all $\mathbf{x}' \in \mathcal{X}$, $\int_{\mathcal{X}} \frac{K_q(\mathbf{x}, \mathbf{x}')}{P_{K_q, \xi_q^*}^{1+s/q}(\mathbf{x})} d\mu(\mathbf{x}) \leq e_{K_q, s, \mu}^s(\xi_q^*)$

Discretisation of μ :

→ Replace μ by μ_N uniform on $\mathcal{X}_N = \{\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(N)}\}$:

→ minimise $e_{K_q, s, \mu_N}^q(\xi) = \left[\text{trace} \left(\frac{1}{N} \mathbf{M}_{K_q}^{-p}(\xi) \right) \right]^{1/p}$ (Φ_p -optimal design, $p = s/q$)

$$\mathbf{M}_K(\xi) = \int_{\mathcal{X}} \text{diag}\{K(\mathbf{x}^{(j)}, \mathbf{x}), j=1, \dots, N\} d\xi(\mathbf{x})$$

Relaxation with $K_{\gamma,\ell}(\mathbf{x}, \mathbf{x}') = \exp[-\|\mathbf{x} - \mathbf{x}'\|^\gamma / (\gamma \ell^\gamma)]$

$$E_{K_{\gamma,\ell},s,\mu}(\mathbf{X}_n) = \ell \gamma^{1/\gamma} \left(\int_{\mathcal{X}} [-\log P_{K_{\gamma,\ell},\xi_n,\epsilon}(\mathbf{x})]^{s/\gamma} d\mu(\mathbf{x}) \right)^{1/s}$$

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Simplification for $\gamma = s$

$$\Rightarrow E_{K_{s,\ell},s,\mu}^s(\mathbf{X}_n) = -s \ell^s \int_{\mathcal{X}} \log P_{K_{s,\ell},\xi_{n,e}}(\mathbf{x}) d\mu(\mathbf{x}) \quad (\rightarrow E_{s,\mu}^s(\mathbf{X}_n) \text{ as } \ell \rightarrow 0)$$

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→ continuous version:

$e_{K_{s,\ell},s,\mu}^s(\cdot)$ is convex (strictly when μ equivalent to Λ and $s \in (0, 2]$) → ET

$$\xi_s^* \text{ is optimal} \Leftrightarrow \text{for all } \mathbf{x}' \in \mathcal{X}, \int_{\mathcal{X}} \frac{K_{s,\ell}(\mathbf{x}, \mathbf{x}')}{P_{K_{s,\ell},\xi_s^*}(\mathbf{x})} d\mu(\mathbf{x}) \leq 1$$

(but ξ_K^* is not of full support even when $\xi_{K_{s,\ell}}^+$ is → Example 5)

Relaxation with $K_{\gamma,\ell}(\mathbf{x}, \mathbf{x}') = \exp[-\|\mathbf{x} - \mathbf{x}'\|^\gamma / (\gamma \ell^\gamma)]$

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Simplification for $\gamma = s$

$$\Rightarrow E_{K_{s,\ell},s,\mu}^s(\mathbf{X}_n) = -s \ell^s \int_{\mathcal{X}} \log P_{K_{e,s,\ell},\xi_{n,e}}(\mathbf{x}) d\mu(\mathbf{x}) \quad (\rightarrow E_{s,\mu}^s(\mathbf{X}_n) \text{ as } \ell \rightarrow 0)$$

→ continuous version:

$e_{K_{s,\ell},s,\mu}^s(\cdot)$ is convex (strictly when μ equivalent to Λ and $s \in (0, 2]$) **→ ET**

$$\xi_s^* \text{ is optimal} \Leftrightarrow \text{for all } \mathbf{x}' \in \mathcal{X}, \int_{\mathcal{X}} \frac{K_{s,\ell}(\mathbf{x}, \mathbf{x}')}{P_{K_{s,\ell},\xi_s^*}(\mathbf{x})} d\mu(\mathbf{x}) \leq 1$$

(but ξ_K^* is not of full support even when $\xi_{K_{s,\ell}}^+$ is **→ Example 5**)

Discretisation of μ :

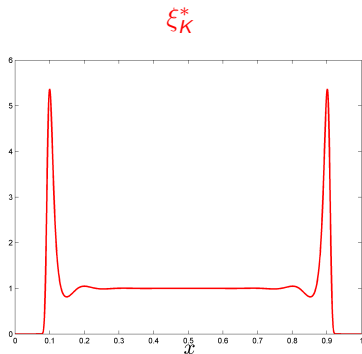
→ Replace μ by μ_N uniform on $\mathcal{X}_N = \{\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(N)}\}$:

→ minimise $e_{K_{s,\ell},s,\mu_N}^s(\xi) = s \ell^s \log \left\{ \det^{-1/N} [\mathbf{M}_{K_{s,\ell}}(\xi)] \right\}$ (D-optimal design)

$$\mathbf{M}_K(\xi) = \int_{\mathcal{X}} \text{diag}\{K(\mathbf{x}^{(j)}, \mathbf{x}), j=1, \dots, N\} d\xi(\mathbf{x})$$

Example 5: $\mathcal{X} = [0, 1]$, $K(x, x') = \exp(-|x - x'|/\ell)$ (Matérn 1/2), $s = q = 1$,
 $\mu = \mathcal{U}_{\mathcal{X}}$ uniform on \mathcal{X}

Numerical determination of ξ_K^* for $\ell = 1/10$ (multiplicative algorithm):

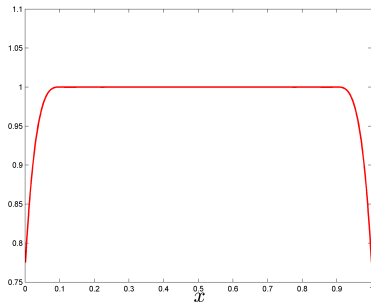
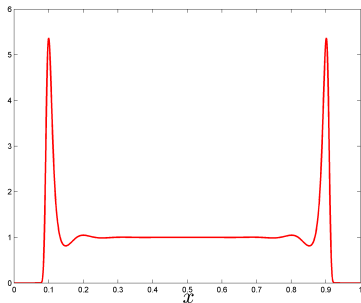


Example 5: $\mathcal{X} = [0, 1]$, $K(x, x') = \exp(-|x - x'|/\ell)$ (Matérn 1/2), $s = q = 1$,
 $\mu = \mathcal{U}_{\mathcal{X}}$ uniform on \mathcal{X}

Numerical determination of ξ_K^* for $\ell = 1/10$ (multiplicative algorithm):

ξ_K^*

$$\int \frac{K(x, z)}{P_{K, \xi_K^*}(z)} d\mu(z)$$

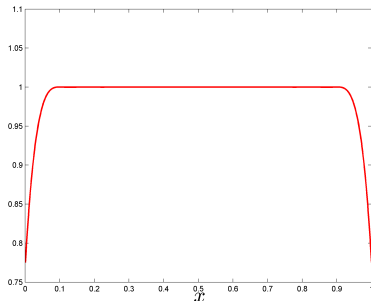
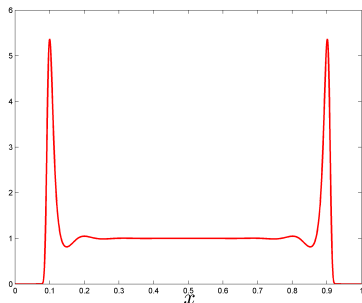


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Numerical determination of ξ_K^* for $\ell = 1/10$ (multiplicative algorithm):

 ξ_K^*

$$\int \frac{K(x, z)}{P_{K, \xi_K^*}(z)} d\mu(z)$$



Exact solution:

$$\ell \geq 1/2 \quad \xi_K^* = \delta_{1/2}$$

$$1/2 > \ell \quad \xi_K^* = \ell(\delta_\ell + \delta_{1-\ell}) + (1 - 2\ell)\Lambda([\ell, 1 - \ell])$$

(and $\xi_K^* \rightarrow \mu = \mathcal{U}_{\mathcal{X}}$ when $\ell \rightarrow 0$)

6 Conclusions

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6 Conclusions

- After kernel relaxation, the packing, covering and quantisation problems are related to standard Φ_p -optimal design, including A- and D-optimal design
- Gradient-type descent (vertex-direction) methods can be used for incremental constructions (\rightarrow kernel herding of machine learning)
- Several theoretical questions remain open and are challenging, concerning the support of a minimum-energy probability measure (related to the existence of a minimum-energy signed measure of total mass one and to the existence of the continuous BLUE in the location model with correlated errors), in connection with the properties of K

Thank you for your attention!

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